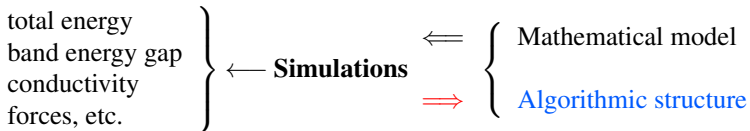


Block Iterative Eigensolvers for Sequences of Dense Correlated Eigenvalue Problems

Birkbeck University, London, June the 29th 2012 | Edoardo Di Napoli

Motivation and Goals

Reverse Simulation



Goal

Increasing the **performance** of large legacy codes by exploiting physical information extracted from the simulations that can be used to **speed-up** the algorithms used in such codes

Outline

Stating the problem: how sequences of generalized eigenproblems arise in all-electron computations

Eigenvectors angle evolution

ALGORITHM \Leftarrow SIM – Exploiting eigenvector collinearity: block iterative eigensolvers

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The Foundations

Investigative framework

Quantum Mechanics and its ingredients

- $$H = -\frac{\hbar^2}{2m} \sum_{i=1}^n \nabla_i^2 - \sum_{i=1}^n \sum_{\alpha} \frac{Z_{\alpha}}{|x_i - a_{\alpha}|} + \sum_{i < j} \frac{1}{|x_i - x_j|}$$
Hamiltonian
- $$\Phi(x_1; s_1, x_2; s_2, \dots, x_n; s_n)$$
Wavefunction

$\Phi: \left(\mathbb{R}^3 \times \{\pm \frac{1}{2}\}\right)^n \rightarrow \mathbb{R}$ high-dimensional anti-symmetric function – describes the orbitals of atoms and molecules. In the *Born-Oppenheimer* approximation, it is the solution of the

Electronic Schrödinger Equation

$$H\Phi(x_1; s_1, x_2; s_2, \dots, x_n; s_n) = \mathcal{E}\Phi(x_1; s_1, x_2; s_2, \dots, x_n; s_n)$$

Density Functional Theory (DFT)

- 1 $\Phi(x_1; s_1, x_2; s_2, \dots, x_n; s_n) \implies \Lambda_{i,a} \phi_a(x_i; s_i)$
- 2 **density of states** $n(\mathbf{r}) = \sum_a |\phi_a(\mathbf{r})|^2$
- 3 In the Schrödinger equation the exact Coulomb interaction is substituted with an effective potential $V_0(\mathbf{r}) = V_I(\mathbf{r}) + V_H(\mathbf{r}) + V_{xc}(\mathbf{r})$

Hohenberg-Kohn theorem

- \exists one-to-one correspondence $n(\mathbf{r}) \leftrightarrow V_0(\mathbf{r}) \implies V_0(\mathbf{r}) = V_0(\mathbf{r})[n]$
- $\exists!$ a functional $E[n] : E_0 = \min_n E[n]$

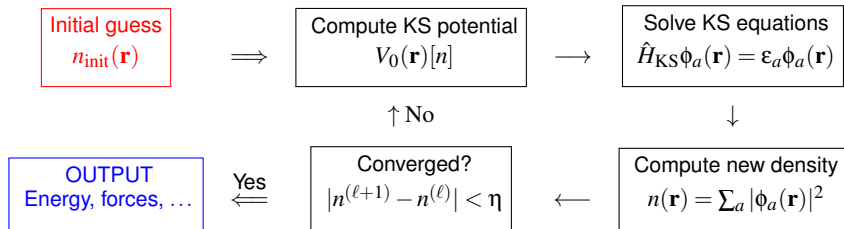
The high-dimensional Schrödinger equation translates into a set of coupled non-linear low-dimensional self-consistent Kohn-Sham (KS) equation

$$\forall a \quad \text{solve} \quad \hat{H}_{\text{KS}} \phi_a(\mathbf{r}) = \left(-\frac{\hbar^2}{2m} \nabla^2 + V_0(\mathbf{r}) \right) \phi_a(\mathbf{r}) = \epsilon_a \phi_a(\mathbf{r})$$

Kohn-Sham scheme and DFT

Self-consistent cycle

Typically this set of equations is solved using an iterative self-consistent cycle



In practice this iterative cycle is much more computationally challenging and requires some form of broadly defined **discretization**

Generalized eigenvalue problems

$$Ax = \lambda Bx$$

A common way of discretizing the KS equations is to expand the wave functions $\phi_a(\mathbf{r})$ on a basis set

$$\phi_a(\mathbf{r}) \longrightarrow \phi_{\mathbf{k},\nu}(\mathbf{r}) = \sum_{|\mathbf{G}+\mathbf{k}| \leq \mathbf{K}_{max}} c_{\mathbf{k},\nu}^{\mathbf{G}} \Psi_{\mathbf{G}}(\mathbf{k}, \mathbf{r})$$

This expansion is then inserted in the KS equations

$$\Psi_{\mathbf{G}}^*(\mathbf{k}, \mathbf{r}) \sum_{\mathbf{G}'} \hat{H}_{\text{KS}} c_{\mathbf{k},\nu}^{\mathbf{G}'} \Psi_{\mathbf{G}'}(\mathbf{k}, \mathbf{r}) = \lambda_{\mathbf{k}\nu} \Psi_{\mathbf{G}}^*(\mathbf{k}, \mathbf{r}) \sum_{\mathbf{G}'} c_{\mathbf{k},\nu}^{\mathbf{G}'} \Psi_{\mathbf{G}'}(\mathbf{k}, \mathbf{r}),$$

and, by defining the matrix entries for the left and right hand side respectively as Hamiltonian $A_{\mathbf{k}}$ and overlap matrices $B_{\mathbf{k}}$,

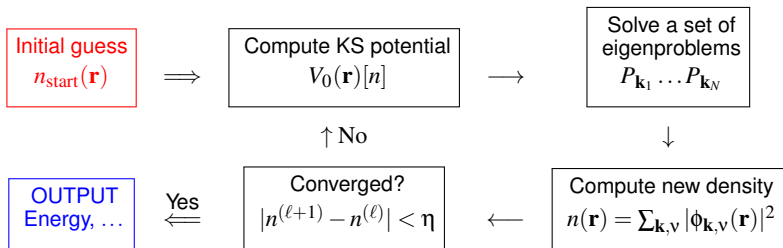
$$[A_{\mathbf{k}} \ B_{\mathbf{k}}]_{\mathbf{G}\mathbf{G}'} = \sum_{\alpha} \int d\mathbf{r} \Psi_{\mathbf{G}}^*(\mathbf{k}, \mathbf{r}) [\hat{H}_{\text{KS}} \hat{\mathbb{1}}] \Psi_{\mathbf{G}'}(\mathbf{k}, \mathbf{r})$$

one arrives at [generalized eigenvalue equations](#) parametrized by \mathbf{k}

$$P_{\mathbf{k}} : \sum_{\mathbf{G}'} (A_{\mathbf{k}})_{\mathbf{G}\mathbf{G}'} c_{\mathbf{k}\nu}^{\mathbf{G}'} = \lambda_{\mathbf{k}\nu} \sum_{\mathbf{G}'} (B_{\mathbf{k}})_{\mathbf{G}\mathbf{G}'} c_{\mathbf{k}\nu}^{\mathbf{G}'} \quad \equiv \quad A_{\mathbf{k}} x_i = \lambda_i B_{\mathbf{k}} x_i.$$

Discretized Kohn-Sham scheme

Self-consistent cycle



Observations:

- 1 A and B are respectively hermitian and hermitian positive definite
- 2 eigenproblems across \mathbf{k} index have different size and we consider them independent from each other (for the moment)
- 3 eigenvectors of problems of same \mathbf{k} are seemingly uncorrelated across iterations i
- 4 $\mathbf{k} = 1:10-100$; $i = 1:20-50$

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Sequences of eigs: an ALGORITHM \Leftarrow SIM case

Sequences of eigenproblems

- Consider the set of generalized eigenproblems $P^{(1)} \dots P^{(\ell)} P^{(\ell+1)} \dots P^{(N)} \neq (P)^N$
- Could this sequence $\{P^{(\ell)}\}$ of eigenproblems **evolve** following a convergence pattern in line with the convergence of $n(\mathbf{r})$?

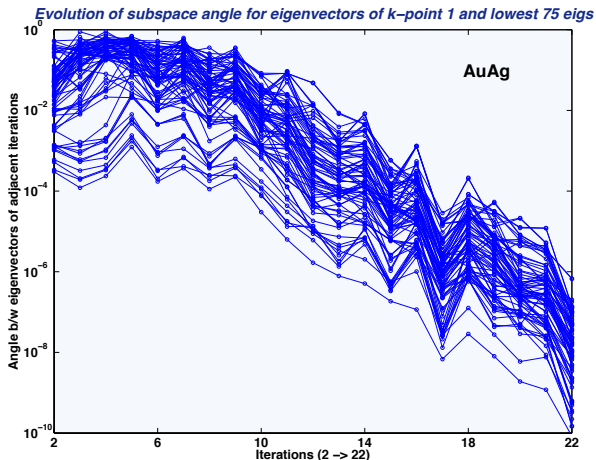
Numerical study:

- studied the evolutions of the angles b/w eigenvectors of successive iterations
- developed a method that establishes systematically a one-to-one correspondence b/w eigenvectors
- collected data on eigenvectors deviation angles
 - 1 analyzed deviation angles at fixed λ for all \mathbf{k} s
 - 2 analyzed deviation angles at fixed \mathbf{k} for all λ s below Fermi Energy

Angle evolution

fixed k

Example: a metallic compound at fixed k



Correlation and its exploitation

- \exists correlation between successive eigenvectors $x^{(\ell-1)}$ and $x^{(\ell)}$
- Angles decrease monotonically with some oscillation
- Majority of angles are small after the first few iterations

Note: Mathematical model \nRightarrow correlation.

Correlation \Leftarrow **systematic analysis** of the simulation.

ALGORITHM \Leftarrow SIM

The stage is favorable to an iterative eigensolver where the eigenvectors of $P^{(\ell-1)}$ are fed to the solve $P^{(\ell)}$

Next stages of the investigation:

- 1 Establish which eigensolvers can exploit the evolution (Implicit Restarted Arnoldi, Krylov-Schur, Subspace Iteration, Davidson-like, etc.)
- 2 Investigate if approximate eigenvectors can speed-up iterative solvers
- 3 Understand if iterative methods be competitive with direct methods for **dense** problems

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Block Iterative Eigensolvers

Two essential properties the iterative algorithms have to comply with:

- 1 the ability to receive as input a **sizable set** of approximate eigenvectors;
- 2 the capacity to **solve simultaneously** for a substantial portion of eigenpairs.

Block iterative methods constitutes the natural choice:

- they accept a variable set of **multiple starting vectors**;
- these methods have a **faster convergence rate** and avoid stalling when facing small clusters of eigenvalues;
- when augmented with **polynomial accelerators** their performance is further improved.

ALGORITHMS: Block Krylov-Schur – Block Chebyshev-Davidson – Chebyshev Subspace Iteration – LOBPCG

Experimental tests setup

Matrix sizes: 2,000 ÷ 5,700

Num of fixed-point iterations: 15 ÷ 30

Num of k-points: 6 ÷ 27

B ill-conditioned

B is in general almost singular.

Examples: $\text{size}(A) = 50 \rightarrow \kappa(A) \approx 10^4$ $\text{size}(A) = 500 \rightarrow \kappa(A) \approx 10^7$

We used the standard form for the problem

$$Ax = \lambda Bx \quad \longrightarrow \quad A'y = \lambda y \quad \text{with} \quad A' = L^{-1}AL^{-T} \quad \text{and} \quad y = L^T x$$

Numerical Study:

- Approx. vs Random solutions against [Iteration Index](#)
- Approx. vs Random solutions against [Spectrum Fraction](#)

Numerical tests were performed using Matlab version R2011b (7.13.0.564) running on an Intel i7 CPU with 8 cores at 2.93 GHz. Four cores and 8 Gb of RAM were fully dedicated to computations

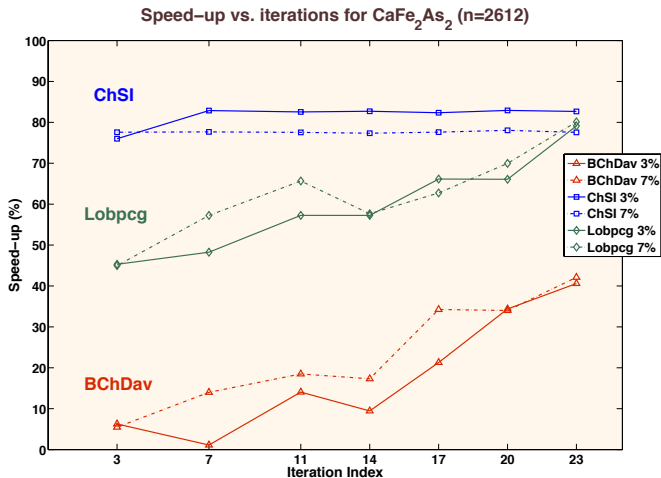


Figure: Comparison between the 3 most effective block iterative eigensolvers for CaFe_2As_2 with respect to the outer-iteration index

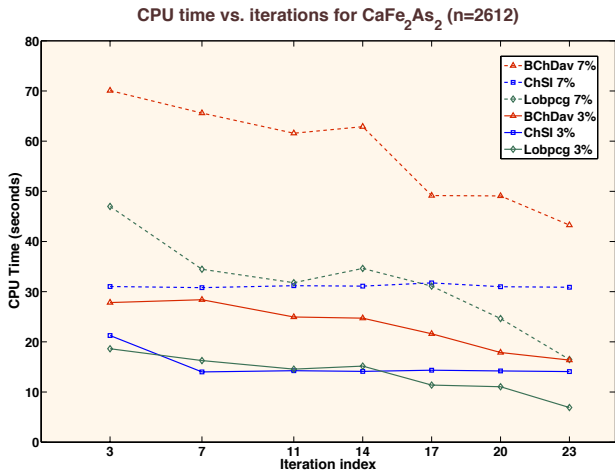


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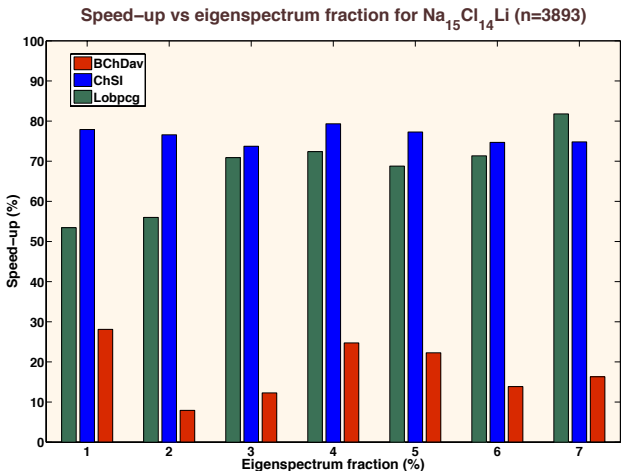


Figure: Comparison between the 3 most effective block iterative eigensolvers for $\text{Na}_{15}\text{Cl}_{14}\text{Li}$ with respect to eigenspectrum fraction

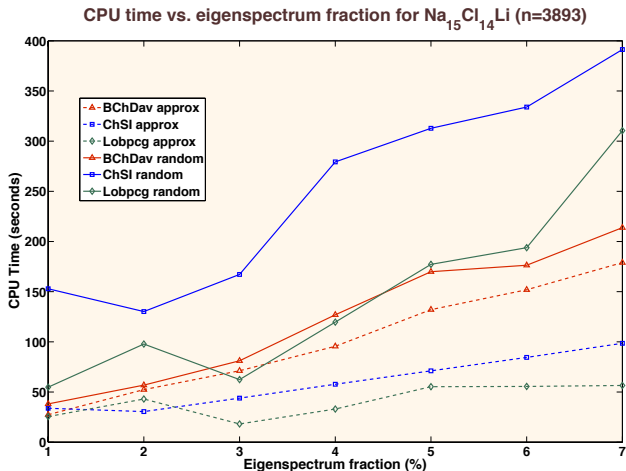


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In summary

All methods allow the possibility of “seeding” the eigensolver with **as many** eigenvectors as needed

1 Chebyshev Subspace Iteration and LOBPCG methods:

- Experience between 55% and 85% speed-up
- The speed-up has little dependence on the eigenspectrum fraction or the iteration index
- Their efficiency highly depend on the efficiency of Matrix-Matrix multiplication sub-routines ⇒ GPUs

2 Block Chebyshev-Davidson method:

- Experiences a speed-up up to 45 %
- The increased “feeding” capacity allows speed-ups even when a substantial fraction of the spectrum is sought after
- Evolution of the sequence implies an increase in speed-ups towards the end of the sequence

Conclusions and future work

- Feeding eigenvectors of $P^{(\ell-1)}$ speed-ups the iterative solver for $P^{(\ell)}$;
- The algorithmic structure of FLAPW could be re-thought to take into consideration our results → **“reverse simulation” can substantially influence the computational paradigm of an application**;
- Conduct a more low-level analysis of speed-up on variants of the investigated algorithms
- Planning the generalization of a block Chebyshev-filtered Subspace Iteration eigensolver with a general interface for the use of approximate solutions;
- Analysis on the structure of the entries of A and B across adjacent iteration seems to suggest an exploitation of low-rank updates for sequences of eigenproblems;
- Correlation may open the road to a reduction of eigenproblem complexity through a sequence of reductions to tridiagonal form.

References

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