- 1. Let's start with a few reading assignments:
 - (a) §19.1 of *Peskin & Schroeder*. Read about the Hamiltonian picture of the axial anomaly in 1 + 1 dimensions.
 - (b) §19.2 of *Peskin & Schroeder*, first two subsections. Read how to evaluate the triangle diagrams using different UV regulators from what I had used in class, namely pointsplitting (subsection 1) and dimensional regularization (subsection 2).
 - (c) §19.2 of *Peskin & Schroeder*, third subsection, and §22.2–3 of *Weinberg*. Read about formal analysis of the axial anomaly stemming from the measure of the fermionic functional integral. Both *Peskin & Schroeder* and *Weinberg* explain regulating the Jacobian of the axial variable transform along the lines I used in class, but pay particular attention too the issue I did not explain, namely why the UV regulator should be a function of the $-\mathcal{P}^2$ operator, $\hat{G} = G(-\mathcal{P}^2/\Lambda^2)$.
- 2. Following up on *Weinberg*'s analysis of the axial anomaly of the fermionic functional integral's measure in d = 4 dimensions, let's generalize it to other *even* spacetime dimensions d = 2n. In any such dimension there a matrix Γ which acts as the γ^5 in 4D — $\Gamma^2 = +1$ while $\Gamma \gamma^{\mu} = -\gamma^{\mu} \Gamma$ for all $\mu = 1, 2, ... d$. Consequently, a massless Dirac fermion in d = 2n dimensions has a classical axial symmetry

$$\Psi(x) \to \exp(i\theta\Gamma)\Psi(x), \qquad \overline{\Psi}(x) \to \Psi(x)\exp(i\theta\Gamma),$$
 (1)

which leads to a classically conserved current

$$J_A^{\mu} = \overline{\Psi} \gamma^{\mu} \Gamma \Psi, \qquad \partial_{\mu} J_A^{\mu} = \text{classically} = 0.$$
 (2)

But when the fermion Ψ is coupled to a gauge field — or a multiplet of such fermions is coupled to a non-abelian gauge field — the axial symmetry is broken by the anomaly, thus

$$\partial_{\mu}J_{A}^{\mu} = -\frac{2}{n!} \left(\frac{-1}{4\pi}\right)^{n} \epsilon^{\alpha_{1}\beta_{1}\alpha_{2}\beta_{2}\cdots\alpha_{n}\beta_{n}} \operatorname{tr}\left(\mathcal{F}_{\alpha_{1}\beta_{1}}\mathcal{F}_{\alpha_{2}\beta_{2}}\cdots\mathcal{F}_{\alpha_{n}\beta_{n}}\right).$$
(3)

Your task is to derive this formula from the UV-regulated Jacobian of the fermionic path integral.

For your information, in any even Euclidean dimension d = 2n,

$$\{\gamma^{\mu}, \gamma^{\nu}\} = +2\delta^{\mu\nu}, \qquad [\gamma^{\mu}, \gamma^{\nu}] = +2i\sigma^{\mu\nu}, \qquad (4)$$

$$\Gamma = i^n \gamma^1 \gamma^2 \cdots \gamma^{2n} \implies \Gamma^2 = +1, \quad \Gamma \gamma^\mu = -\gamma^\mu \Gamma \; \forall \mu = 1, \dots, 2n, \tag{5}$$

for any
$$d = 2n$$
 Dirac matrices $\gamma^{\alpha}, \dots, \gamma^{\omega}$: $\operatorname{tr}(\Gamma \gamma^{\alpha} \gamma^{\beta} \cdots \gamma^{\omega}) = (-2i)^n \epsilon^{\alpha \beta \cdots \omega},$ (6)

for any *n* spin matrices
$$\sigma^{\alpha\beta}, \dots, \sigma^{\psi\omega}$$
: $\operatorname{tr}(\Gamma\sigma^{\alpha\beta}\cdots\sigma^{\psi\omega}) = 2^n \epsilon^{\alpha\beta\cdots\psi\omega}$. (7)

- 3. This problem exists in two versions, 3A and 3B. If you are familiar with the differential form language, please solve problem 3A; otherwise, please solve problem 3B. The two versions are physically equivalent to each other, but the math is written in a different language.
- (3A) In the differential form language, eqs. (3) become

$$d * J_A = -\frac{2}{n!} \left(\frac{-1}{4\pi}\right)^n \operatorname{tr}\left(\mathcal{F} \wedge \mathcal{F} \wedge \dots \wedge \mathcal{F}\right)_{n \text{ times}}.$$
(8)

The 2n-forms on the RHS of these formulae are exact:

$$Q_{(2n)} \stackrel{\text{def}}{=} \operatorname{tr} \left(\mathcal{F} \wedge \mathcal{F} \wedge \dots \wedge \mathcal{F} \right)_{n \text{ times}} = d\Omega_{(2n-1)}$$
(9)

where $\Omega_{(2n-1)}$ — constructed as traces of appropriated products of the $\mathcal{A} = gA$ gauge fields (1 forms) and $\mathcal{F} = gF$ tensions fields (2 forms) — are the *Chern–Simons* forms. Specifically,

$$\Omega_{(1)} = \operatorname{tr}(\mathcal{A}) \qquad [\text{abelian } \mathcal{A} \text{ only}], \tag{10.a}$$

$$\Omega_{(3)} = \operatorname{tr} \left(\mathcal{A} \wedge \mathcal{F} - \frac{i}{3} \mathcal{A} \wedge \mathcal{A} \wedge \mathcal{A} \right), \tag{10.b}$$

$$\Omega_{(5)} = \operatorname{tr} \left(\mathcal{A} \wedge \mathcal{F} \wedge \mathcal{F} - \frac{i}{2} \mathcal{A} \wedge \mathcal{A} \wedge \mathcal{A} \wedge \mathcal{F} - \frac{1}{10} \mathcal{A} \wedge \mathcal{A} \wedge \mathcal{A} \wedge \mathcal{A} \wedge \mathcal{A} \right), \quad (10.c)$$

etc.

(a) Verify eq. (9) for 2n = 2, 4, 6 and $\Omega_{(2n-1)}$ as in eqs. (10).

The Chern–Simons forms allow us define a conserved axial current as

$$*J_{AC} = *J_A + \frac{2}{n!} \left(\frac{-1}{4\pi}\right)^n \Omega_{(2n-1)}, \qquad d*J_{AC} = 0.$$
(11)

Howover, the price of this conservation is the loss of gauge invariance: Alas, the Chern– Simons forms are non guage invariant.

Nevertheless, the gauge variations of the Chern–Simons forms are closed, $d(\delta\Omega_{(2n-1)}) = 0$. Moverover, for the infinitesimal gauge transforms

$$\delta \mathcal{A} = -D\Lambda = -d\Lambda - i\mathcal{A}\Lambda + i\Lambda\mathcal{A}, \qquad \delta \mathcal{F} = -i\mathcal{F}\Lambda + i\Lambda\mathcal{F}$$
(12)

(for infinitesimal $\Lambda(x)$), the first variations of the Chern–Simons forms are not only closed but exact,

$$\delta\Omega_{(2n-1)} = -dH_{(2n-2)} \tag{13}$$

where $H_{(2n-2)}$ is a (2n-2)-form constructed as a trace of a product of Λ and a polynomial of the \mathcal{A} and \mathcal{F} forms. In particular,

$$H_{(0)} = \operatorname{tr}(\Lambda) \quad \text{[abelian } \mathcal{A} \text{ only]},$$
 (14)

$$H_{(2)} = \operatorname{tr}(\Lambda \, d\mathcal{A}) = \operatorname{tr}(\Lambda(\mathcal{F} - i\mathcal{A} \wedge \mathcal{A})), \tag{15}$$

$$H_{(4)} = \operatorname{tr}\left(\Lambda \, d(\mathcal{A} \wedge d\mathcal{A} + \frac{i}{2}\mathcal{A} \wedge \mathcal{A} \wedge \mathcal{A})\right)$$

$$= \operatorname{tr}\left(\Lambda \left(\mathcal{F} \wedge \mathcal{F} - \frac{i}{2}(\mathcal{F} \wedge \mathcal{A} \wedge \mathcal{A} + \mathcal{A} \wedge \mathcal{F} \wedge \mathcal{A} + \mathcal{A} \wedge \mathcal{A} \wedge \mathcal{F}) - \frac{1}{2}\mathcal{A} \wedge \mathcal{A} \wedge \mathcal{A} \wedge \mathcal{A}\right)\right).$$

$$(16)$$

Verify these formulae for 2n = 2, 4, 6.

Note: eq. (14) is trivial, while eq. (15) should be similar to problem 2 of the Fall 2024 midterm exam. But eq. (16) needs to be verified from scratch.

PS: Besides the axial anomaly in d = 2n dimensions, the 2*n*-forms $Q_{(2n)}$, the Chern-Simons forms $\Omega_{(2n-1)}$, and the $H_{(2n-2)}$ forms are also useful in other spacetime dimensions. In particular, the Chern-Simons 3-form can be used in 3D to give the gauge bosons a topological mass term, as we saw during the Fall 2024 midterm exam.

Towards the end of the Spring semester, we shall see that the $H_{(4)}$ form — reduced from 6 spacetime dimensions down to 4 — governs the non-abelian gauge anomaly. In terms of the anomalous variation of the effective action of the gauge field,

$$\Delta_{\text{gauge}} S_E^{\text{eff}}[\mathcal{A}_{\mu}(x)] = -\frac{1}{16\pi^2} \int_{\text{4d space}} H_{(4)}, \qquad (17)$$

where the trace in eq. (16) is taken over the species of LH Weyl fermions minus a similar trace over the RH Weyl fermion species. Likewise, the non-abelian gauge anomalies in other even spacetime dimensions are also related to the $H_{(2n-2)}$ forms for 2n = d + 2.

(3B) In any even dimension d = 2n, the right hand side of the anomaly equation (3) is always a total derivative,

$$\epsilon^{\alpha_1\beta_1\cdots\alpha_n\beta_n} \operatorname{tr}\left(\mathcal{F}_{\alpha_1\beta_1}\cdots\mathcal{F}_{\alpha_n\beta_n}\right) = \partial_{\mu}\Omega^{\mu}_{(2n-1)}$$
(18)

where $\Omega^{\mu}_{(2n-1)}$ is some polynomial in gauge fields $\mathcal{A}^{\nu} = g A^{\nu}$ and $\mathcal{F}^{\rho\sigma} = g F^{\rho\sigma}$, for example

in
$$d = 2$$
, $\Omega^{\mu}_{(1)} = 2\epsilon^{\mu\nu} \operatorname{tr}(\mathcal{A}_{\nu})$ [abelian A_{ν} only],
in $d = 4$, $\Omega^{\mu}_{(3)} = 2\epsilon^{\mu\nu\rho\sigma} \operatorname{tr}\left(\mathcal{A}_{\nu}\mathcal{F}_{\rho\sigma} - \frac{2i}{3}\mathcal{A}_{\nu}\mathcal{A}_{\rho}\mathcal{A}_{\sigma}\right)$, (19)
in $d = 6$, $\Omega^{\mu}_{(5)} = 2\epsilon^{\mu\nu\rho\sigma\alpha\beta} \operatorname{tr}\left(\mathcal{A}_{\nu}\mathcal{F}_{\rho\sigma}\mathcal{F}_{\alpha\beta} - iA_{\nu}\mathcal{A}_{\rho}\mathcal{A}_{\sigma}\mathcal{F}_{\alpha\beta} - \frac{2}{5}\mathcal{A}_{\nu}\mathcal{A}_{\rho}\mathcal{A}_{\sigma}\mathcal{A}_{\alpha}\mathcal{A}_{\beta}\right)$,

etc., etc. The $\Omega^{\mu}_{(2n-1)}$ vectors are equivalent to (2n-1)-index totally antisymmetric tensors called the *Chern–Simons forms*, and those forms play many important roles in gauge theory and string theory. In particular, we may use the $\Omega^{\mu}_{(2n-1)}$ to define a conserved axial current

$$J_A^{\mu} \to J_{AC}^{\mu} = \overline{\Psi} \gamma^{\mu} \Gamma \Psi + \frac{1}{n!} \left(\frac{-1}{4\pi}\right)^n \times \Omega^{\mu}_{(2n-1)}.$$
(20)

(Its conservation follows from eqs. (3) and (18).) However, the price of this current conservation is the loss of gauge invariance: the original axial current J_A^{μ} is gauge invariant, but the J_{AC}^{μ} is not.

(a) You task is to verify eqs. (18) for d = 2, 4, 6.

The Chern–Simons vectors (19) are not gauge invariant, but their variations under the infinitesimal gauge transforms are total derivatives of antisymmetric tensors,

$$\delta\Omega^{\mu}_{(2n-1)} = -2\partial_{\nu}H^{\mu\nu}_{(2n-2)}, \qquad H^{\mu\nu}_{(2n-2)} = -H^{\nu\mu}_{(2n-2)}. \tag{21}$$

Specifically, for d = 2n = 2, 4, 6:

in
$$d = 2$$
, $H_{(0)}^{\mu\nu} = \epsilon^{\mu\nu} \operatorname{tr}(\Lambda)$ [abelian \mathcal{A}_{ν} only],
in $d = 4$, $H_{(2)}^{\mu\nu} = 2\epsilon^{\mu\nu\rho\sigma} \operatorname{tr}(\Lambda \times \partial_{\rho}\mathcal{A}_{\sigma})$, (22)
in $d = 6$, $H_{(4)}^{\mu\nu} = 4\epsilon^{\mu\nu\rho\sigma\alpha\beta} \operatorname{tr}(\Lambda \times \partial_{\rho}(\mathcal{A}_{\sigma}\partial_{\alpha}\mathcal{A}_{\beta} + \frac{i}{2}A_{\sigma}\mathcal{A}_{\alpha}\mathcal{A}_{\beta}))$.

(b) Verify eqs. (21) for these H tensors.

Note: for d = 2 eq. (21) is trivial, while for d = 4 it's very similar to problem 2(b) of the Fall²2024 midterm exam. But for d = 6 you have to work it out from scratch.